

How to Remove the Look-Ahead of Top-Down Tree Transducers

Sebastian Maneth

University of Edinburgh

with Joost Engelfriet and Helmut Seidl

DLT 2014 - Екатеринбург

Outline

1. Top-Down Tree Transducers (with and wo Look-Ahead)
2. Difference Trees
3. Canonical Transducers
4. Difference Tuples
5. Main Results
6. Future

1. Tree Transducers

Generalize to ranked (ordered) trees the finite-state transducer aka “Generalized Sequential Machine” **GSM** [Ginsburg 1962]

- Top-Down Tree Transducer **TOP**
[Thatcher 1970, “Generalized² Sequential Machine Maps”]
[Rounds 1970, “Mappings and Grammars on Trees”]
- Bottom-Up Tree Transducer **BU**
[Thatcher 1970]

invented as model for

- *linguistics* transformational grammars
- *compiler theory* syntax-directed translations of context-free languages

Recent application: XML

1. Tree Transducers

Generalize to ranked (ordered) trees the finite-state transducer aka “Generalized Sequential Machine” **GSM** [Ginsburg 1962]

→ Top-Down Tree Transducer **TOP**

Cave **TOPs** are more complicated than **GSMs**

→ input subtrees may be processed multiple times (“**copying**”) or not at all (“**deletion**”)

→ size increase is **polynomial** or **exponential** [Aho,Ullman1971]

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- TOP with **regular Look-Ahead TLA** [Engelfriet 1977]

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Advantages of **TLA**

Composition Closure: **linear TLA's**
deterministic TLA's

Power: **DBU** \subseteq **DTLA**

Functions: **TLA*** \cap **FUNCT** = **DTLA** [Engelfriet 1978]

→ Natural for XPath filters (often depend on input trees that are deleted)

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Advantages of **TOP**

→ 1-Pass Computable (allows bounded memory stream processing)

→ Canonical Normal Form [Engelfriet,Maneth,Seidl 2008]

→ Myhill-Nerode & Gold-style learning [Lemay,Maneth,Niehren 2010]

Our Problem

Is it decidable for a **DTLA** (**D**eterministic **T**op-down tree transducer with **L**ook-**A**head) whether there exists an equivalent **DTOP**?

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Is it decidable for a **DTLA** whether there exists an equivalent **DTOP**?

On **strings** (DGSMs) easy:

→ transform DGSM-LA into GSM

→ try to determinize (“twinning property” [Choffrut 1977])

Twinning property: (runs do “the same” in a loop)

If $q_0(uwx) \Rightarrow^* a_1 q(wx) \Rightarrow^* a_1 b_1 q(x)$
 $q_0(uwx) \Rightarrow^* a_2 p(wx) \Rightarrow^* a_2 b_2 p(x)$

then

$$a_1 b_1 a_1^{-1} = a_2 b_2 a_2^{-1}$$

→ only check **uw** of length $< 2|Q|^2$

Note
DTLA $\not\subseteq$ **TOP**

DTLAs

$M = (Q, S, \Delta, R, A, \mathbf{P}, d)$

Q: states

S: ranked alphabet of input symbols

Δ : ranked alphabet of output symbols

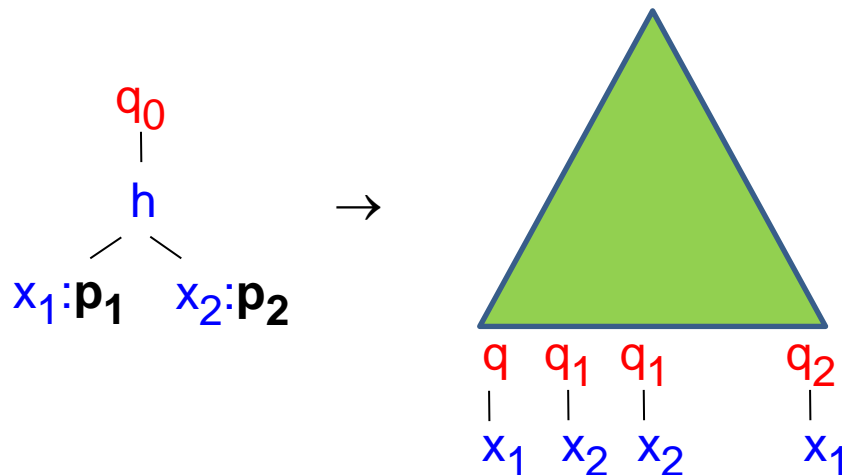
R: rules

A: axioms $A(\mathbf{p})$ for every \mathbf{p} in \mathbf{P}

\mathbf{P} : look-ahead states

d: look-ahead transitions (deterministic and total)

Rules:



DTLAs

$$M_1 = (\mathbf{Q}, \mathbf{S}, \Delta, R, A, \mathbf{P}, d)$$

$$d(a) = \mathbf{p}_a$$

$$d(b) = \mathbf{p}_b$$

$$d(h(\mathbf{p}_a/\mathbf{p}_b)) = \mathbf{p}_a/\mathbf{p}_b$$

$$M_1(h^n(a)) = a$$

$$M_1(h^n(b)) = h^n(b)$$

$$A(\mathbf{p}_a) = a$$

$$A(\mathbf{p}_b) = q(x_0)$$

$$\begin{array}{c} q \\ | \\ h \\ | \\ x_1 \cdot \mathbf{p}_b \end{array} \rightarrow \begin{array}{c} h \\ | \\ q \\ | \\ x_1 \end{array}$$

$$\begin{array}{c} q \\ | \\ b \end{array} \rightarrow b$$

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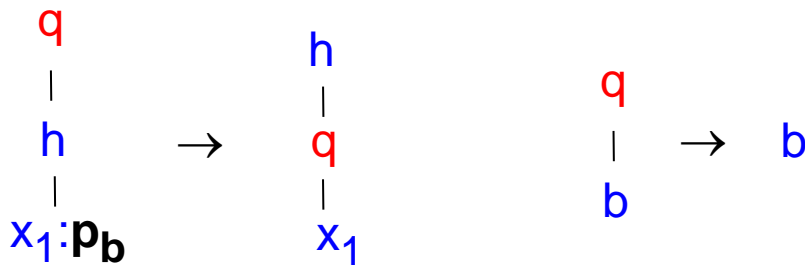
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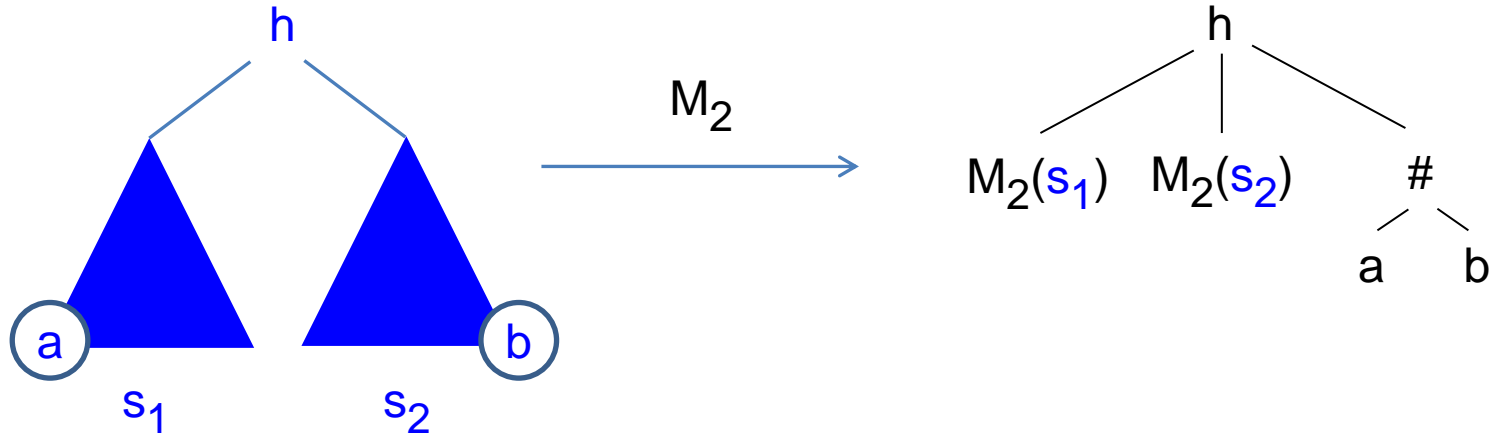
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→ Can M_1 be realized without look-ahead (i.e., by a **DTOP**)?

DTLAs



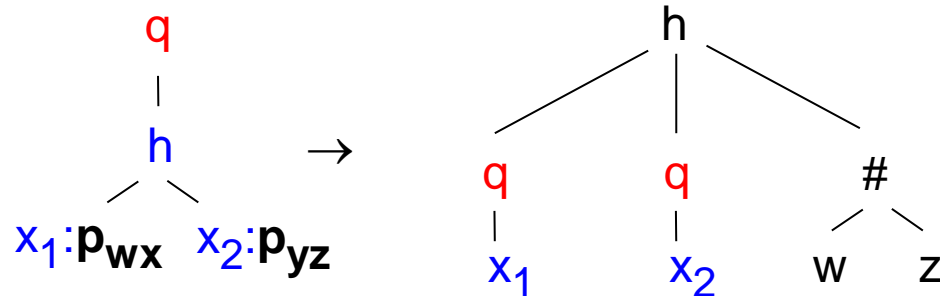
$$\mathbf{P} = \{p_{xy} \mid x, y \in \{a, b\}\}$$

$$d(a) = p_{aa} \quad d(b) = p_{bb}$$

$$d(h(p_{wx}, p_{yz})) = p_{wz} \quad \text{for all } w, x, y, z \in \{a, b\}$$

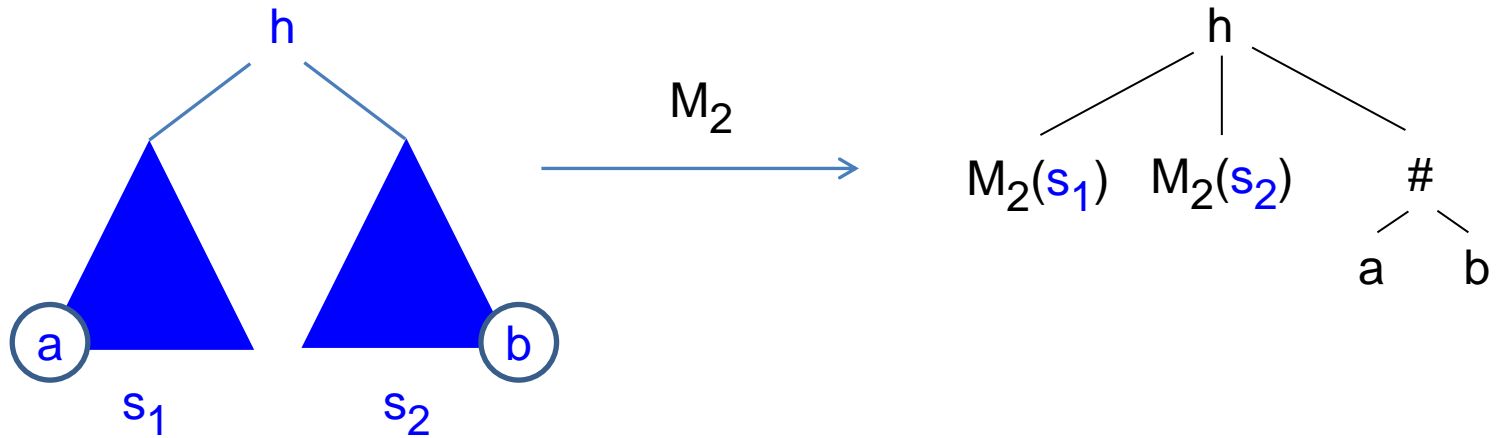
$$A(p_{yz}) = q(x_0)$$

$$q(a/b) \rightarrow a/b$$



DTLAs

→ Can M_2 be realized w/o look-ahead (i.e., by a **DTOP**)?



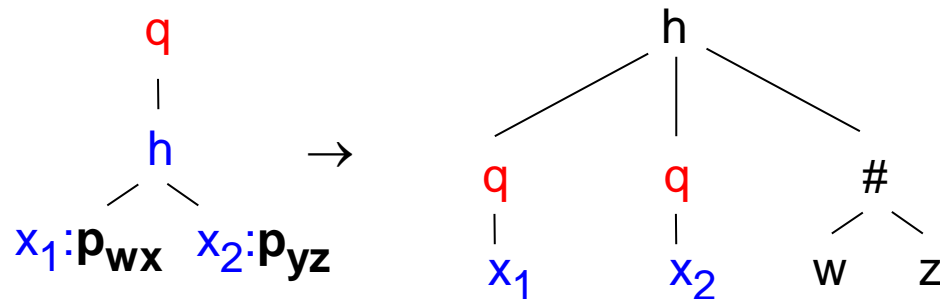
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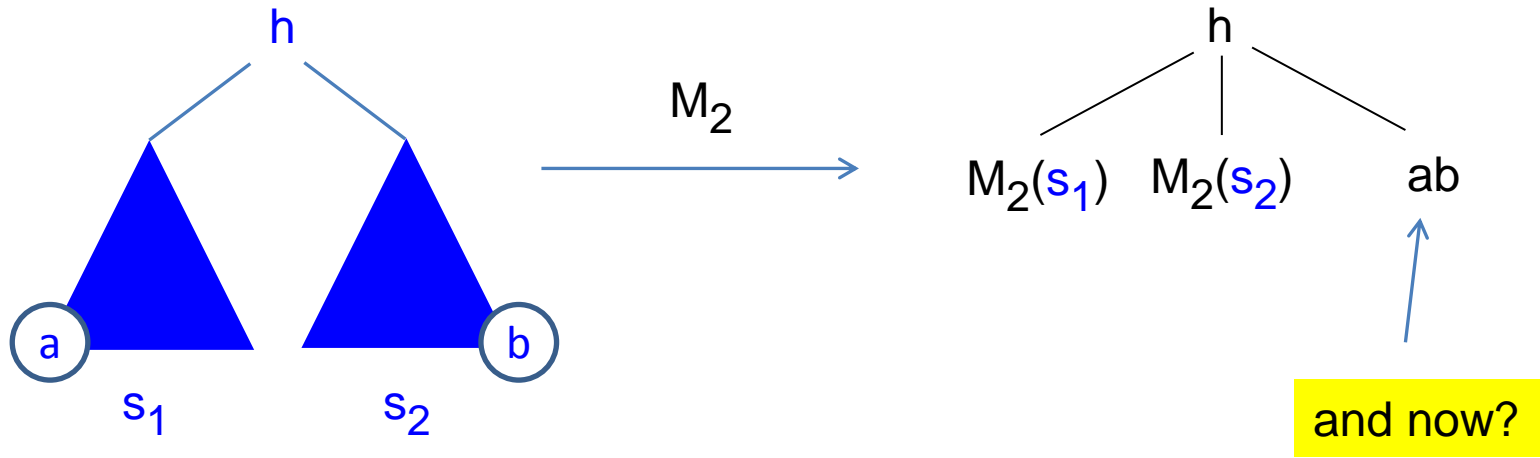
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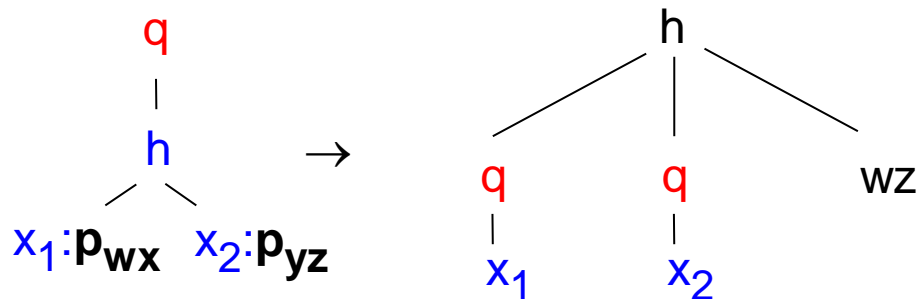
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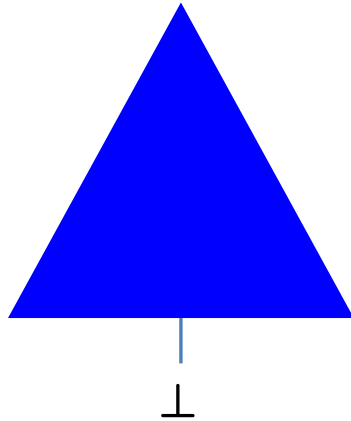
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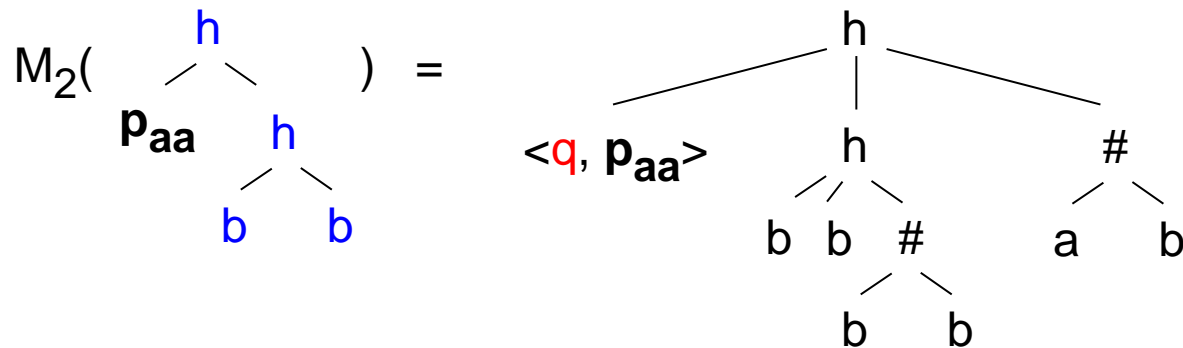
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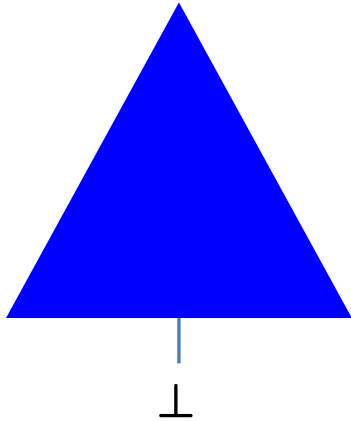
Context C = input tree with exactly one \perp -leaf

$$C[\mathbf{p}] = C[\perp \leftarrow \mathbf{p}]$$

$M(C[\mathbf{p}])$ = output tree with leaves $\langle \mathbf{q}, \mathbf{p} \rangle$ where \mathbf{q} reaches the \mathbf{p} -leaf



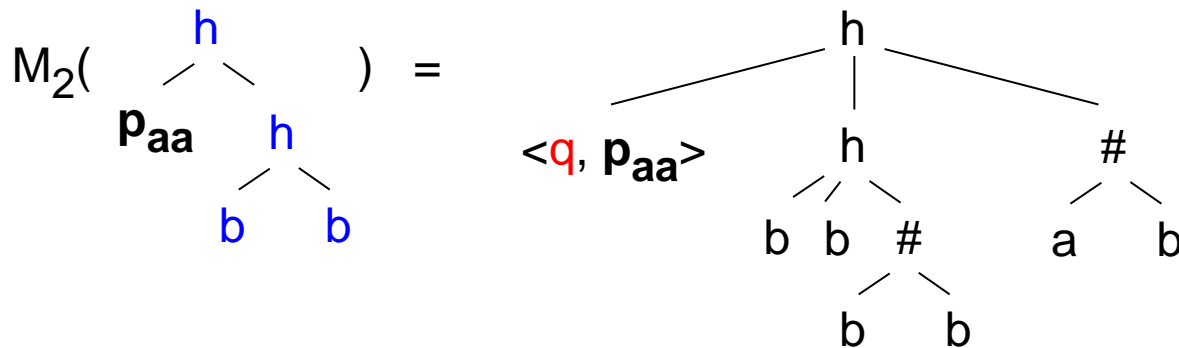
Replacement Lemma



Context C = input tree with exactly one \perp -leaf

$$C[p] = C[\perp \leftarrow p]$$

Lemma $\forall s$ with $d(s)=p$, $M(C[s]) = M(C[p])[\langle q, p \rangle \leftarrow M_q(s) \mid q \in Q]$.

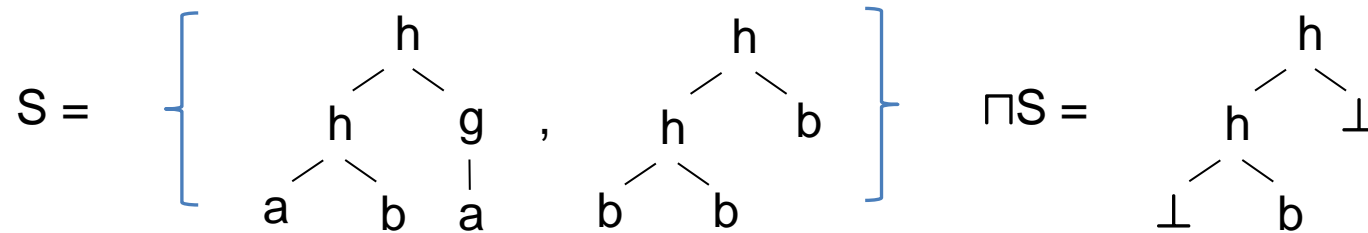


2. Difference Trees

How can we characterize output that a **DTLA** produces due to its look-ahead information?

S = set of trees

$\sqcap S$ = largest common prefix of the trees in S



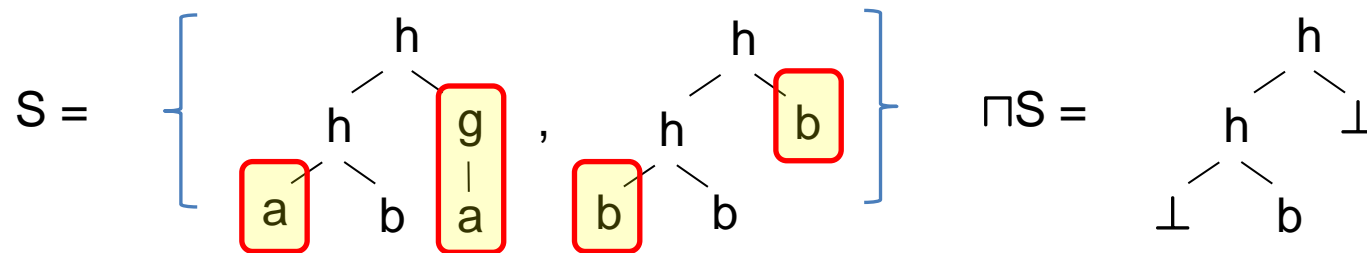
Difference tree = subtree of s at v for $s \in S$
and v a \perp -node in $\sqcap S$

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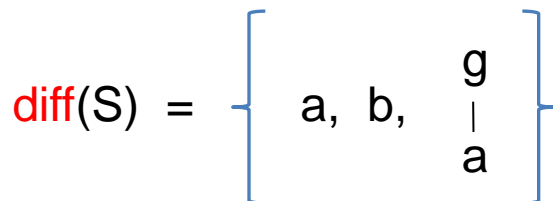
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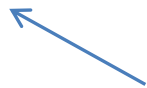
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\mathbf{p}, \mathbf{p}' : distinct look-ahead states

$M(\mathbf{C}[\mathbf{p}]) \sqcap M(\mathbf{C}[\mathbf{p}'])$ = output **not** depending on look-ahead \mathbf{p}/\mathbf{p}'

$\text{diff}(\{ M(\mathbf{C}[\mathbf{p}]), M(\mathbf{C}[\mathbf{p}']) \})$ = trees that M outputs due to \mathbf{p}/\mathbf{p}' -information

$\text{diff}(M) := \bigcup \{ \text{diff}(\{ M(\mathbf{C}[\mathbf{p}]), M(\mathbf{C}[\mathbf{p}']) \}) \mid \mathbf{C} \in \text{Con}, \mathbf{p}, \mathbf{p}' \in P \}$



Measure of how much M makes use of its look-ahead

2. Difference Trees

$$\begin{aligned} M_1(h^n(\mathbf{p}_a)) &= a \\ M_1(h^n(\mathbf{p}_b)) &= h^n(\langle \mathbf{q}, \mathbf{p}_b \rangle) \end{aligned} \quad \begin{array}{l} \swarrow \\ \searrow \end{array} \quad \sqcap = \perp$$

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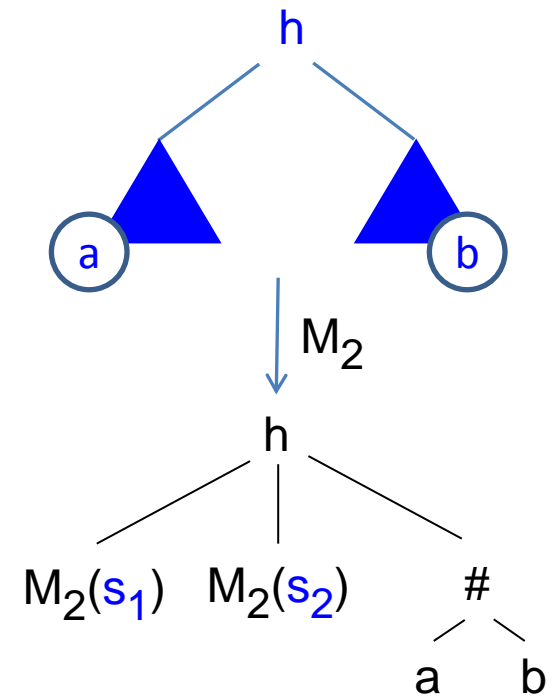
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$$\text{diff}(M_2) = ?$$

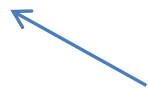


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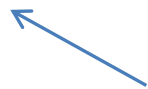
$$\text{diff}(M_2) = \{a, b\} \cup \{ \langle \mathbf{q}, \mathbf{p} \rangle \mid \mathbf{p} \in \mathbf{P} \}$$

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$$\text{diff}(M_1) = \{a\} \cup \{h^n(\langle \mathbf{q}, \mathbf{p}_b \rangle) \mid n \geq 0\} \quad \leftarrow \text{infinite}$$

$$\text{diff}(M_2) = \{a, b\} \cup \{\langle \mathbf{q}, \mathbf{p} \rangle \mid \mathbf{p} \in \mathbf{P}\} \quad \leftarrow \text{finite}$$

Define $\text{maxdiff}(M)$ = maximal height of a tree in $\text{diff}(M)$
if $\text{diff}(M)$ is finite

difference bound of M = number m such that
height(s) $\leq m$ for every $s \in \text{diff}(M)$

3. Canonical Transducers

[EMS 2008] For every **DTOP** M an equivalent **canonical DTOP** $\text{can}(M)$ can be constructed.

canonical = (1) each output node is produced as **early** as possible
(2) different states are inequivalent

Two **DTOPs** are equivalent iff their **canonical DTOPs** are equal (up to renaming of states).

Theorem 1 For every **DTLA** M an equivalent **canonical DTLA** $\text{can}(M)$ with same look-ahead automaton as M can be constructed s.t.
 $\text{maxdiff}(M) - 8^{|M|^3} \leq \text{maxdiff}(\text{can}(M)) \leq \text{maxdiff}(M) + 8^{|M|^3}$.

3. Canonical Transducers

M: canonical DTLA

N: canonical DTOP

such that M is equivalent to N

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→ $N(C)$ is a prefix of $M(C[p])$ $\forall C$ and $p \in P$

“**aheadness mapping** from N to M” = replaces $\langle q, p \rangle$ by tree in $T_{\Delta}(Q_M)$

Lemma

There is a *unique* **aheadness mapping** φ from N to M.

4. Difference Tuples

s/v = subtree of s at node v

$$\text{diftup}(s_1, \dots, s_n) = \{(s_1/v, \dots, s_n/v) \mid v \text{ is } \perp\text{-node in } \Pi\{s_1, \dots, s_n\}\}$$

$\mathbf{P} = \{\mathbf{p}_1, \dots, \mathbf{p}_n\}$ (in that order)

$$\text{diftup}(M) = \cup \{ \text{diftup}(M(\mathbf{C}([\mathbf{p}_1])), \dots, M(\mathbf{C}[\mathbf{p}_n])) \mid \mathbf{C} \in \text{Con} \}$$

M, N : canonical and equivalent

φ : aheadness mapping from N to M

Let $\psi(\mathbf{q}) = (\varphi(\mathbf{q}, \mathbf{p}_1), \dots, \varphi(\mathbf{q}, \mathbf{p}_n))$ for $\mathbf{q} \in Q_N$.

Lemma ψ is a bijection between Q_N and $\text{diftup}(M)$.

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4. Difference Tuples

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→ so, we “only” need to check finiteness of $\text{diff}(M)$ (for M canonical)
plus some other properties

For instance:

$M(f(a,a)) \rightarrow 1$

$M(\text{any other tree}) \rightarrow 0$

$\text{diff}(M)$ is finite, but translation is not in **DTOP**

5. Main Result

Theorem It is decidable for given **DLTA** M and difference bound m for M , whether there exists an equivalent **DTOP** N , and if so, N can be constructed.

Proof

- make M canonical (adds $8^{|M|^3}$ to m)
- successively construct aheadness mapping and corresponding rules
- finally check if resulting transducer is equivalent to M

Main Crux

How to compute a difference bound for a given **DTLA**?!

DTLA is

- **linear** if every x_i occurs at most once in every rhs of a rule
- **nonerasing** if no rhs is of the form $q(x_i)$

Theorem It is decidable for a **linear nonerasing DTLA** M whether there exists an equivalent **DTOP** N (then N can be constructed)

Proof By (difficult) pumping arguments show that $37*|M|^5$ is a difference bound.

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-
- can be extended to “**ultralinear**” and “**bounded erasing**”.
See [\[arXiv\]-version](#) (57 pages)

6. Future

Extend to

→ **partial** ultralinear and bounded erasing **DTLAs**
(our proofs are for total transducers)

→ **all DTLAs** 😊

→ Algorithm to construct equivalent **DTLA** with **minimal** **|P|**

(would enable Myhill-Nerode and Gold-style learning)

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>- THE END -<

Thanks for your Attention!